

# Absolute encoder TRT with PROFINET interface



- Singleturn and multiturn versions
- Contactless, wear-free sensor system
- High vibration and shock resistance thanks to the robust mechanical design
- Position and speed signal
- Resolution: up to 8192 steps/360° ↯ (13-bit)  
(HW version 2: 16384 (14 bit))
- Measuring range: up to 4096 revolutions
- Protection type: up to IP69K
- PI certified PROFINET interface
- Programmable via PROFINET
- Special slewing ring software for non-reversing operation available
- Hardware version 2 in preparation

## Design and function

Recording of the angular position and revolutions by means of Hall sensors - multiturn version with absolute multiturn transmission for up to 4096 revolutions - data output plus parameterisation and diagnosis via PROFINET.

Robust housing manufactured from seawater-resistant aluminium or stainless steel - stainless steel shaft - ball bearing with radial shaft seal - magnetical sensor system - electrical connection via M12 connector or cable outlet.

The Profinet interface according to IEC 61158/61784 or PNO specifications order No. 2.712 and 2.722, version 2.2, is integrated into the model series TRT absolute encoders. Real time classes 1 - 3 are supported, i.e. Real Time (RT) and Isochronous Real Time (IRT) plus the requirements of conformance class C.

The integrated 2-fold switch enables the TWK PROFINET absolute encoders to be used in star, tree and line network topologies.

An exhaustive description of integration into a PROFINET network can be found in the manual [TRT12887](#).

In the version with code type "S" the TRT offers a slewing ring functionality. This converts the sensor shaft position value into the position of a slewing ring or a rotary table.

The slew ring encoder permits the adjustment of the number of teeth of the slew ring and of the encoder gear-wheel via the encoder parameters. In this way all gear ratios are possible and the encoder can be adapted to any slew ring by the user. The output values are the position of the slew ring in degrees (resolution adjustable) and his velocity in degree/time basis (time basis adjustable).

## PROFINET properties

- Real Time (RT) and Isochronous Real Time (IRT)
- Device exchange without interchangeable medium or programming device
- Prioritised start-up (Fast Start Up)
- Media redundancy possible
- Firmware update via Profinet
- Programming via Profinet

# Absolute encoder model TRT

## Technical data

### Input data \*

- 4-byte position data and 2-byte speed data

### Output data \*

- 4-byte reference value

### Electrical data

- Sensor system: Magnetical
- Operating voltage: + 9 VDC to + 36 VDC (polarity reversal protection)
- Power consumption: < 3 W, switch-on current < 500 mA
- Resolution: 4096 steps/360° - (12-bit) or 8192 steps/360° - (13-bit)  
(HW version 2: 14 bit bzw. 16384 steps)
- Measuring range: 4096 revolutions (only multiturn version)
- Total number of steps: Singleturn: 12 or 13 bit, multiturn: 24 or 25 bit  
(HW version 2: 14 bzw. 26 bit)
- Absolute accuracy: ± 0.2 % (with reference to one revolution), singleturn version ± 0.1 %  
(HW version 2: 0,1 %, singleturn version 0,05% )
- Internal updating time: 1 ms
- Output code: Binary
- Code path: CW/CCW
- Speed signal: 16-bit, with prefix, unit: steps/gate time  
(gate time adjustable in the 10 ... 1000 ms range, default: 10 ms)
- Internal updating time of the speed signal: 1 ms

### PROFINET data

- MAC address: 00:0E:CF:XX:XX:XX  
The relevant, current MAC address is located on the model plate.
- Transfer technology: 100 Base-TX
- Transfer rate: 10/100 Mbit/s
- Line length: Max. 100 m (between two subscribers)
- Minimum transmission cycle: 250 µs

### Mechanical data

- Operating speed: 1.000 rpm max. (optional 10.000 rpm)
- Angular acceleration: 10<sup>5</sup> rad/s<sup>2</sup> max.
- Moment of inertia (rotor): 20 gcm<sup>2</sup>
- Operating torque: ≤ 8 Ncm (at 500 rpm)
- Starting torque: ≤ 4 Ncm
- Perm. shaft load: 250 N axial, 250 N radial ( Flange form HP: 500 N axial and radial)
- Bearing service life \*\*: > 10<sup>9</sup> revolutions
- Weight: ca. 0.450 kg

### Environmental data

- Operating temperature range: - 40 °C to + 85 °C
- Storage temperature range: - 20 °C to + 60 °C (due to packaging)
- Resistance
  - To shock: 500 m/s<sup>2</sup>; 6 ms (DIN EN 60068-2-27)
  - To vibration: 250 m/s<sup>2</sup>; 5 ... 2000 Hz (DIN EN 60068-2-6)
- EMC standards: EN 61000-6-4 (interference emission)  
EN 61000 6-2 (interference immunity)
- Protection type: IP 66/IP 67, with cable output IP 68, IP 69K optional (DIN EN 60529)
- Salt mist test: Test Kb according to IEC 60068-2-52

\* From the point of view of the control system.

\*\* These values apply at maximum shaft load. Higher values are achievable at lower loads.

## Absolute encoder model TRT

### Technical data

#### Electrical connection

- PROFINET: M12 connector D-coded 4-pin for bus in / bus out, socket or cable outlet
- Supply: M12 connector A-coded 4-pin, pins or cable outlet

#### Cable outlet PROFINET (optional)

- Cable type: PROFINET Type-C, 4 x 0.36 mm<sup>2</sup> (AWG22)
- Cable jacket: PUR, color: green
- Temperatur range: - 40 °C to + 70 °C
- Outer diameter: 6.5 mm ± 0.2 mm
- Min. bend radius: 5 x d fixed installation, 10 x d freely movable

#### Cable outlet power supply (optional)

- Cable type: 2 x 0.75 mm<sup>2</sup>, shielded
- Cable jacket: PUR, color: gray
- Temperatur range: - 40 °C to + 80 °C fixed installation, - 5 °C to + 70 °C freely movable
- Outer diameter: 6 mm
- Min. bend radius: 6 x d fixed installation, 15 x d freely movable

## Absolute encoder model TRT

### Technical data

#### Programmable parameters

##### Standard encoder

| Parameter                     | Value range   | Parameter description  |
|-------------------------------|---|--|
| Scaling                       | Off/On  |  |
| Code path                     | CW/CCW  | CW (clockwise): ascending values on rotation clockwise<br>CCW (counter clockwise): descending values on rotation clockwise (viewed looking at the shaft)   |
| Resolution [steps/360°]       | 1 ... 4096 (8192)*  | Steps per revolution (360°)  |
| Total number of steps [steps] | 1 ... 16,777,216 (33,554,432) or 4096 (8192) for singleturn encoder** | Overall measuring range  |
| Gate time                     | 10 ... 1000 ms  | Time basis for speed registration  |
| Reference value               | 0 ... total number of steps -1  | For adaptation to the application, the position value can be set to any value within the measuring range. Once programmed, a reference value can be set via bit 0 in the control word (output data). |

(The values in brackets apply to the TRTxx-xxx8192R4096C4MTxx)

\* HW version 2: 16384

\*\* HW version 2: 67108864 bzw. 16384

##### Slew ring encoder

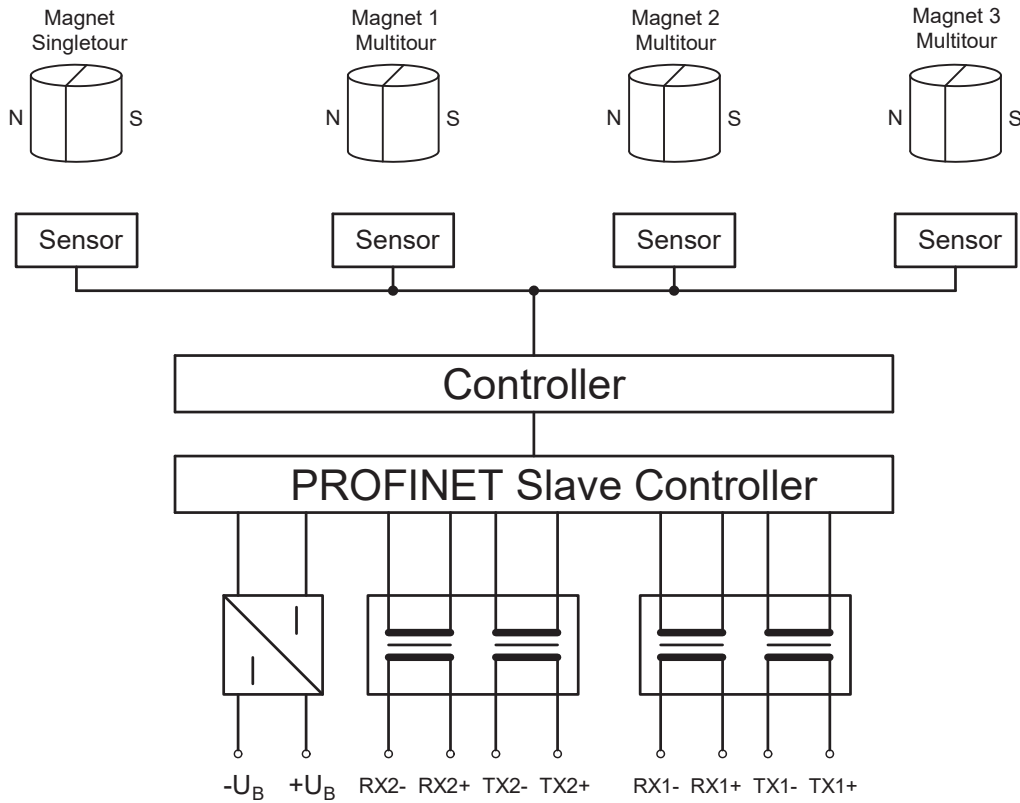
| Parameter                                | Value range               | Parameter description   |
|--|---------------------------|---|
| Code path                                | CW/CCW                    | CW (clockwise): ascending values on rotation clockwise<br>CCW (counter clockwise): descending values on rotation clockwise (viewed looking at the shaft)  |
| Number of teeth slewing ring             | 1 ... 65535               | Number of teeth of the machine*s slewing ring   |
| Number of teeth encoder pinion           | 1 ... 65535               | Number of teeth of the encoder pinion which gears in the slew ring  |
| Resolution position [steps]              | 1 ... 8192 x i            | Desired resolution of the slew ring position, e.g. 3600 for a resolution of 0,1°. The maximum possible value depends on the gear ration i.  |
| Resolution for speed calculation [steps] | 1 ... 8192 x i            | The resolution of the slew ring used for the velocity calculation. This parameter can be adjusted independent of the parameter "Resolution position", e.g. 36000 for a velocity resolution of 0,01° / gate time. The maximum possible value depends on the gear ration i. |
| Gate time [ms]                           | 10 ... 1000               | Time basis of the velocity measurement  |
| Reference value [steps]                  | 1 ... resolution position | To adapt to the users application the encoder can be set to any value within the measuring range. The preset function is processed via the output values and can be executed in the user programm of the PLC.   |

t = Gear ratio *Number of teeth slewing ring to Number of teeth encoder pinion*

# Absolute encoder model TRT

## Electrical connector

### Block diagram



### PROFINET M12 connector connection assignment (Port 1 and Port 2)

| Connection                | Port 1 / Port 2 |       |        |      |
|---------------------------|-----------------|-------|--------|------|
| Connector output Pin code | 1               | 2     | 3      | 4    |
| Cable output Core color * | yellow          | white | orange | blue |
| Signal                    | TX+             | RX+   | TX-    | RX-  |

### Supply M12 connector connection assignment

| Connection                | + 24 VDC                    |   |                          |   |
|---------------------------|-----------------------------|---|--------------------------|---|
| Connector output Pin code | 1                           | 2 | 3                        | 4 |
| Cable output Core color * | white                       | — | brown                    | — |
| Signal                    | + V <sub>S</sub> (+ 24 VDC) | — | - V <sub>S</sub> (0 VDC) | — |

\* Industrial Ethernet cable colours according to ISO / IEC 8802-3.

**Absolute encoder model TRT****Diagnosis-LED`s**

| <b>UB<br/>(VS)</b> | <b>Link 1<br/>(L1)</b> | <b>Link 2<br/>(L2)</b> | <b>Status<br/>(NS)</b> | <b>Description</b>  |
|--------------------|------------------------|------------------------|------------------------|---|
| <b>green</b>       | <b>green</b>           | <b>green</b>           | <b>green/red</b>       |   |
| on                 |                        |                        |                        | Operating voltage available                                       |
|                    | on                     |                        |                        | Network connection established                                    |
|                    |                        | on                     |                        | Network connection established                                    |
|                    |                        |                        | green                  | Data exchange, device in operation and OK                         |
|                    |                        |                        | gren flashing          | Network connection o.k. but no connection to a PROFINET controler |
|                    |                        |                        | red, slow flashing     | Firmware download mode  |
|                    |                        |                        | red flashing           | Impermissible parameter or preset value                           |
|                    |                        |                        | Fast red flashing      | Device error  |
|                    |                        |                        | red                    | Connection to the PROFINET controller disrupted                   |

# Absolute encoder model TRT

## Order number

|     |    |   |   |   |      |   |      |    |   |   |    |                    |
|-----|----|---|---|---|------|---|------|----|---|---|----|--------------------|
| TRT | 58 | - | K | A | 8192 | R | 4096 | C4 | M | T | 01 | → Standard version |
|-----|----|---|---|---|------|---|------|----|---|---|----|--------------------|

### Electrical and / or mechanical variants\*:

- 01 Standard
- 11 Protection type IP69K

### Output:

- T 100Base-TX

### Electrical connection:

- M Standard, 3 connectors radial
- Mx Connector output radial (x = number of outputs\*\*)
- Tx Connector output axial (x = number of outputs\*\*)
- Ky Cable output radial (y = cable length)
- Ly Cable output axial (y = cable length)

### Profile:

- C4 Standard, PROFINET

### Measuring range:

#### Singleturn: leave blank

1 ... 4096 Revolutions

### Output code:

- R Binary code, position value format integer32
- W Binary code, position value format 2x integer16, resolution not adjustable
- S Binary code, position of the slew ring in integer32

### Resolution:

- 4096 steps / 360° ↯ (for output code S enter always 8192)
- 8192
- 16384 (HW version 2)

### Housing material:

- A Aluminium housing
- S Stainless steel (1.4305) housing
- V Stainless steel (1.4404) housing

### Flange form:

- |     |    |  |
|-----|----|--|
| 58  | K  | Clamped flange, shaft 10 mm with flat  |
|     | KF | Clamped flange, shaft 10 mm with woodruff key                                |
|     | KP | Clamped flange, shaft 10 mm with parallel key (recommended for safety)       |
|     | KZ | Clamped flange, shaft for play-compensating toothed gear ZRS                 |
|     | S  | Synchro flange, shaft 6 mm   |
|     | SR | Synchro flange, clamping shaft 12 mm (torque plate see accessories)          |
|     | ST | Synchro flange, shaft 6 mm with flat   |
| 64  | HP | Heavy duty flange for shaft loads up to 500 N, shaft 10 mm with parallel key |
|     | NZ | Cam switch flange, shaft for play-compensating toothed gear ZRS              |
| 65  | S  | Synchro flange, shaft 12 mm  |
|     | SP | Synchro flange, shaft 12 mm with parallel key                                |
| 66  | K  | Clamped flange, shaft 10 mm with flat  |
|     | KP | Clamped flange, shaft 10 mm with parallel key                                |
| 90  | MP | Mounting flange, shaft 12 mm with parallel key                               |
| 105 | M  | Mounting flange, shaft 12 mm   |
|     | MP | Mounting flange, shaft 12 mm with parallel key                               |

### Design form:

TRT T-Series multi turn with PROFINET interface

\* The basic versions according to the data sheet bear the number 01. Deviations are identified with a variant number and are documented in the factory.

\*\* Number of outputs:

- 1 = Hybrid
- 2 = 1x power supply, 1x PROFINET
- 3 = 1x power supply, 2x PROFINET

## Absolute encoder model TRT

### Accessories, documentation, GSD file

#### Accessories (to be ordered separately)

- Straight mating connector
  - STK4GP81** for PROFINET in/out (Zinc die-cast nickel-plated), see data sheet [STK14570](#)
  - STK4GP110** for PROFINET in/out (stainless steel 1.4404), see data sheet [STK14569](#)
  - STK4GS60** for the supply voltage (Zinc die-cast nickel-plated), see data sheet [STK14572](#)
  - STK4GS104** for the supply voltage (stainless steel 1.4404), see data sheet [STK14571](#)
- Angled mating connector
  - STK4WP116** for PROFINET in/out, see data sheet [STK15518](#)
  - STK4WS61** for the supply voltage, see data sheet [STK14675](#)
- Connecting cable
  - KABEL-xxx-114** Industrial Ethernet data cable with M12 connectors, D-coded, moulded on at both ends. Standard lengths: 1, 2, 3 and 5 m (xxx = length in metres), see data sheet [KBL14673](#)
  - KABEL-xxx-118** Industrial Ethernet data cable with M12 connector to RJ 45, IP 20 (xxx = length in metres), see data sheet [KBL14655](#)
- Couplings
  - BKK** Folding bellows coupling, large, see data sheet [BKK11840](#)
  - BKM** Folding bellows coupling, small, see data sheet [BKM11995](#)
  - KK14N** Clamp coupling, see data sheet [KK12301](#)
- Toothed gear
  - ZRS** Play-compensating toothed gear [ZRS11877](#)
- Torque plate
  - ZMS** see data sheet [ZMS12939](#)
- Further installation accessories and securing clamps are available according to data sheet [MZ10111](#).

#### Documentation, GSD file, etc.

The following documents plus the GSD file, a bitmap and example programmes can be found in the Internet under [www.twk.de/en](http://www.twk.de/en) in the documentation area, model TRT.

- Data sheet TRT12886
- Manual No. [TRT12887](#)



# Absolute encoder model TRT

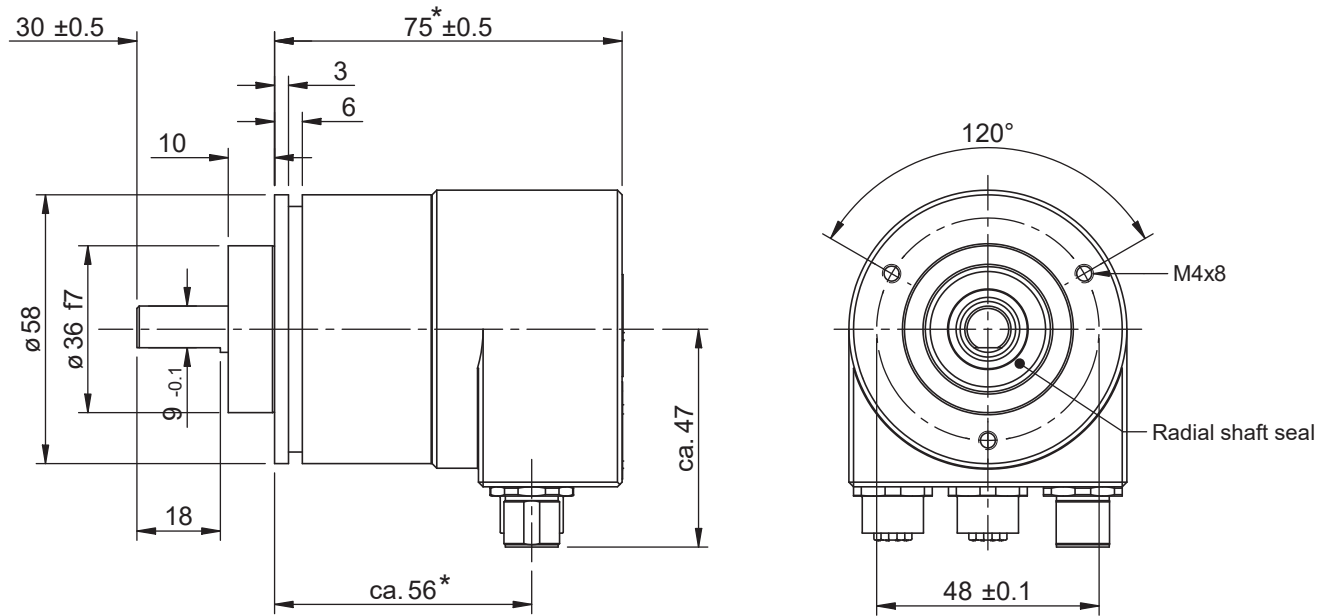
## Installation drawings

### Standard design

**Design form 58 with clamped flange**, order number: TRT58-KA8192R4096C4MT01

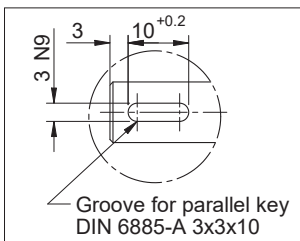
Shaft  $\varnothing$  10 mm

### Dimensions in mm

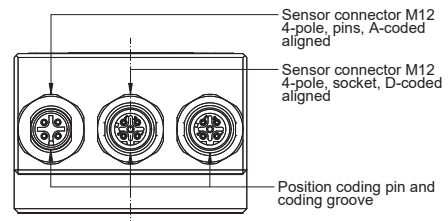


\* Singleturn version 14 mm shorter

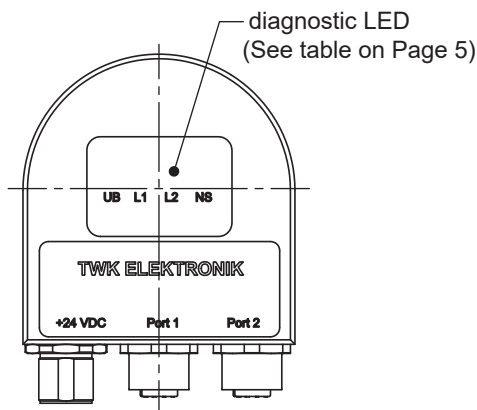
■ Optional: Shaft "P" with groove and parallel key



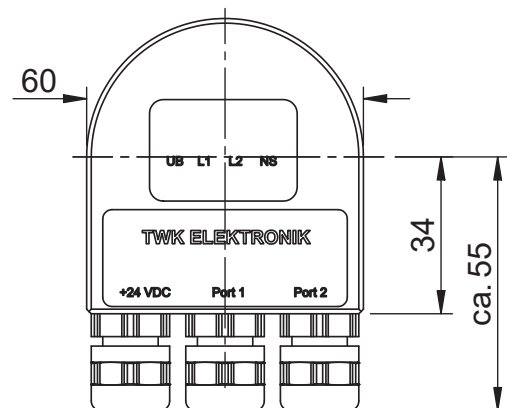
### Connector view with M12-connector



### Rear view with connector M12



### Rear view with cable output



# Absolute encoder model TRT

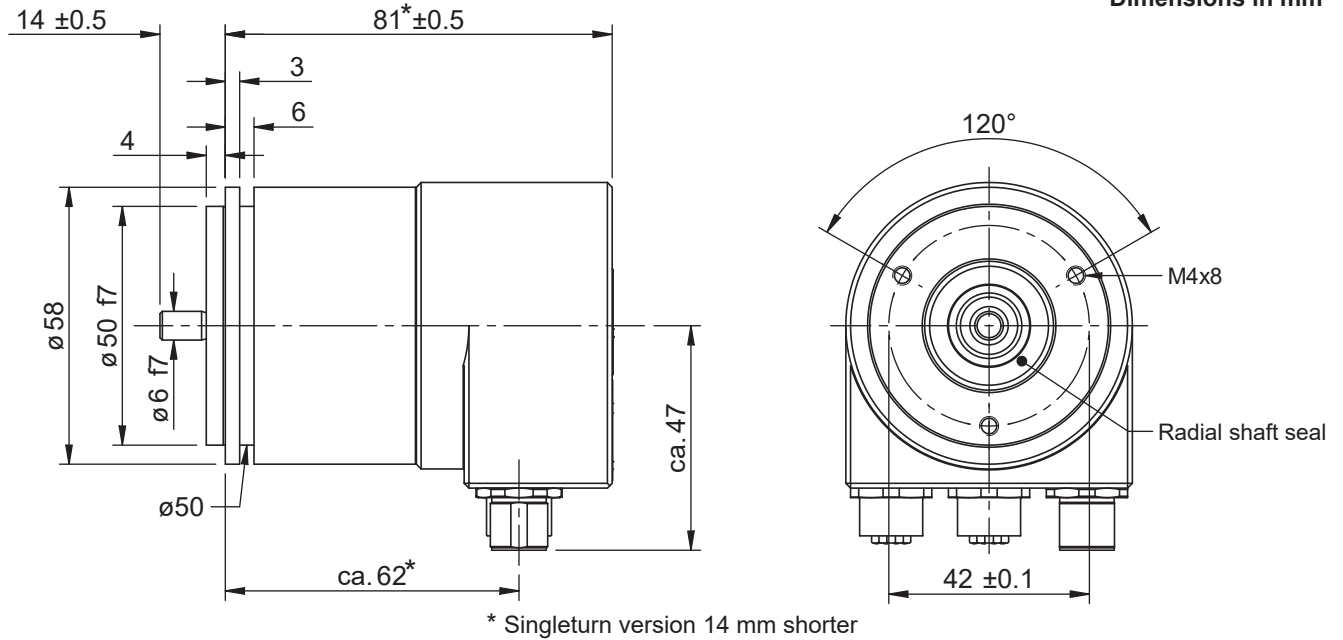
## Installation drawings

### Further possible designs

**Design form 58 with synchroniser flange, order number: TRT58-SA8192R4096C4MT01**

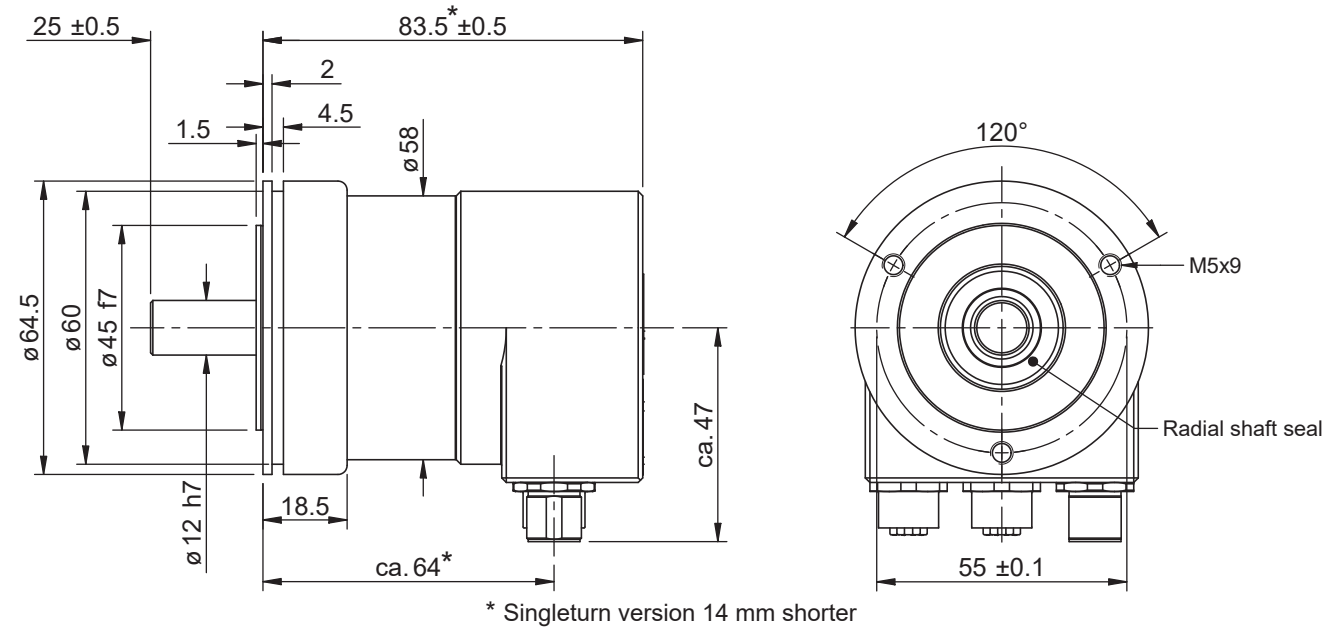
Shaft  $\varnothing$  6 mm

Dimensions in mm

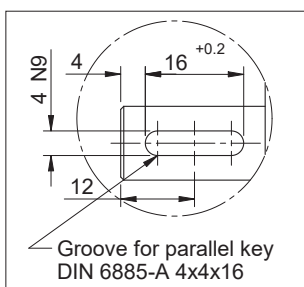


**Design form 65 with synchroniser flange, order number: TRT65-SA8192R4096C4MT01**

Shaft  $\varnothing$  12 mm



■ Optional: Shaft "P" with groove and parallel key



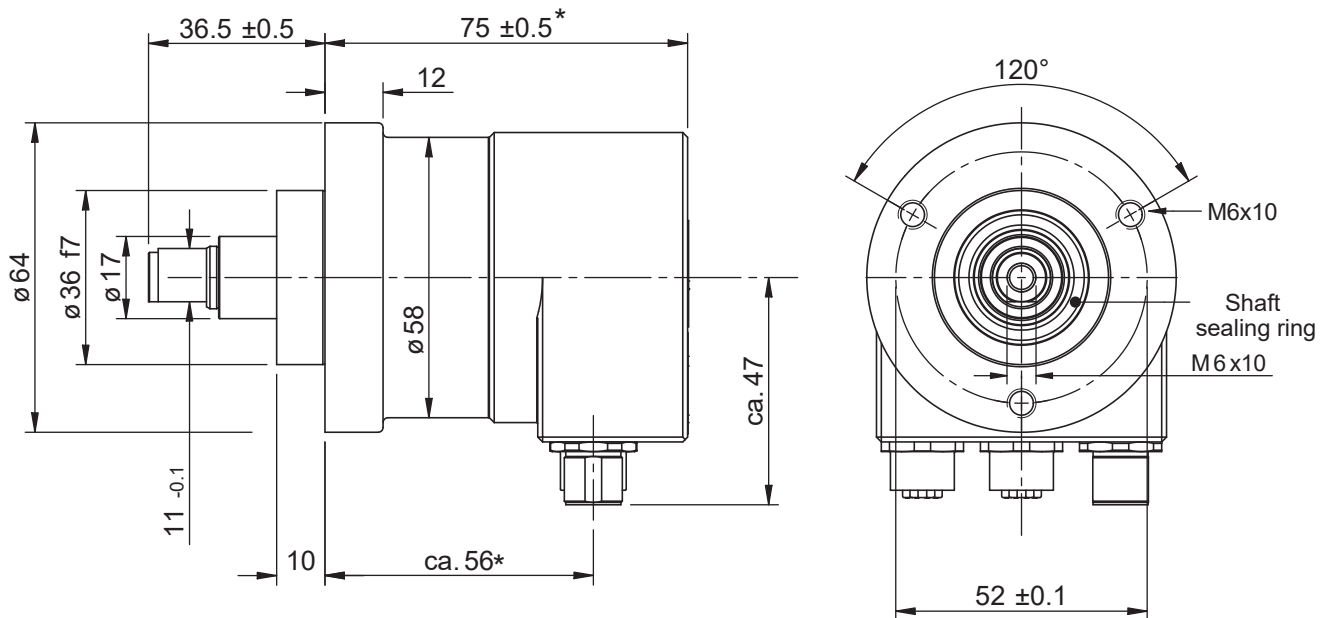
# Absolute encoder model TRT

## Installation drawings

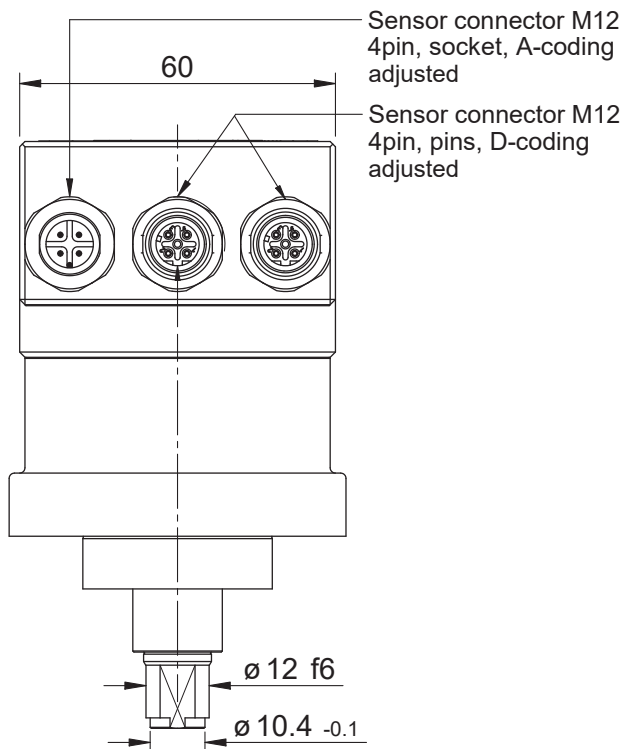
**Design form 64 with switching cam encoder flange, order number: TRT64-NZA8192R4096C4MT01**

Shaft  $\varnothing$  12 mm with flattened area, for mounting the toothed gear

Dimensions in mm



\* Singleturn version 14 mm shorter

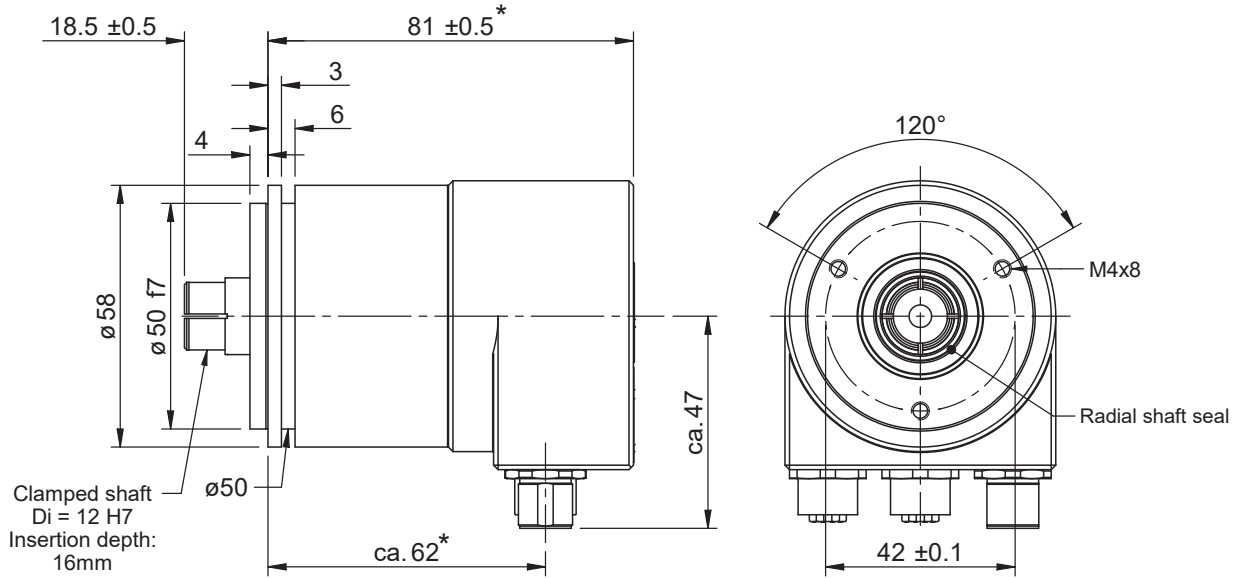


# Absolute encoder model TRT

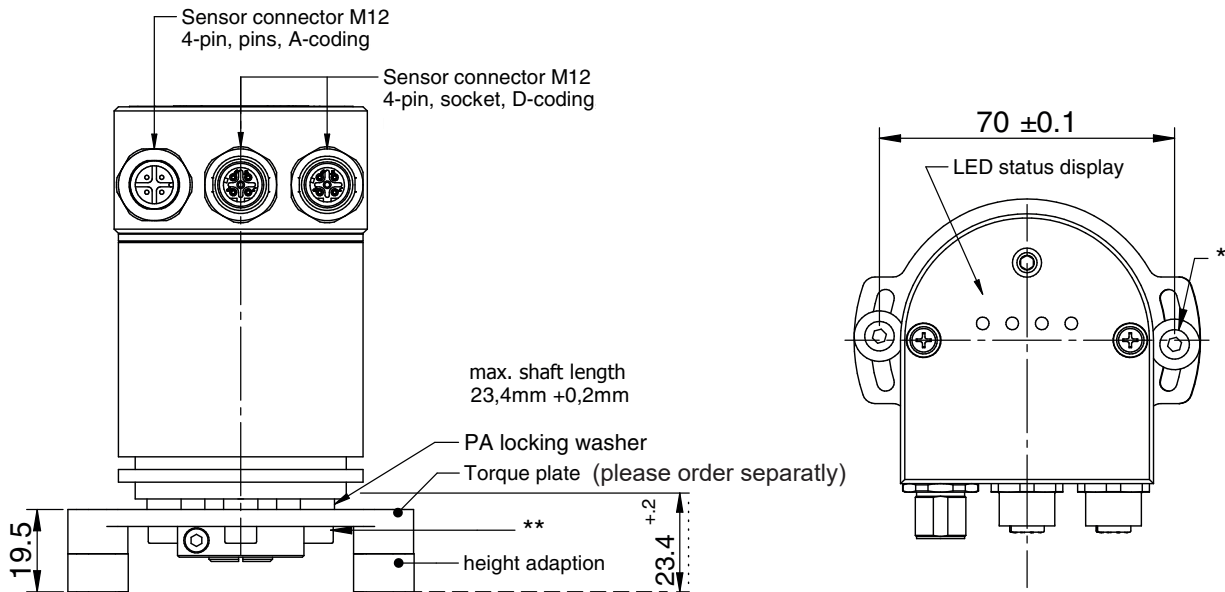
## Installation drawings

**Design form 58 with synchroniser flange and clamped shaft, order number: TRT58-SRA8192R4096C4MT01**  
 Shaft  $\varnothing$  12 mm (other shaft diameters on request)

### Dimensions in mm

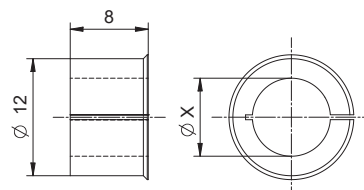
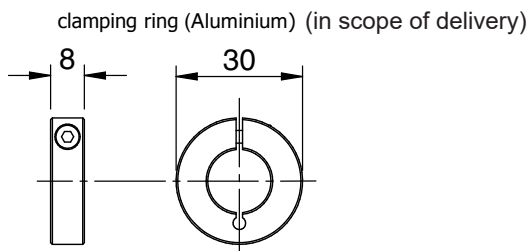


\* Singleturn version 14 mm shorter



### Reducing bush (please order separatly)

Ordering code: ZRH-A-12-X  
 X = 6, 6,35, 8, 9,53, 10



\* 2x screw DIN 912 M4x30 (VA) with 2x locking washer (VA) and 2x flat washer DIN 9021-4,3.

\*\* 3x screw DIN 912 M4x10 (VA) with 3x locking washer (VA).



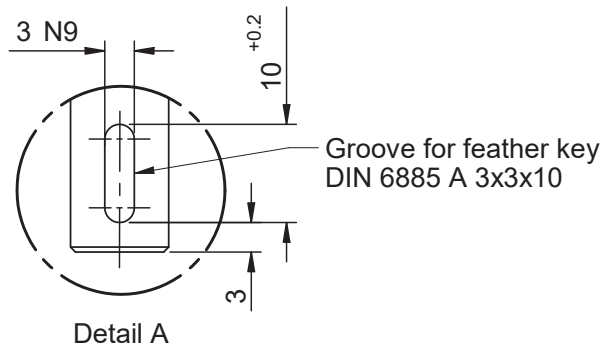
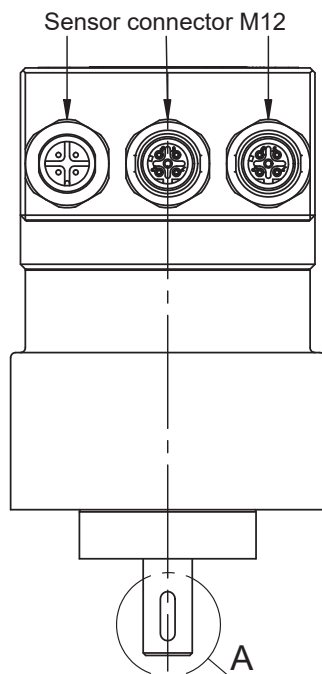
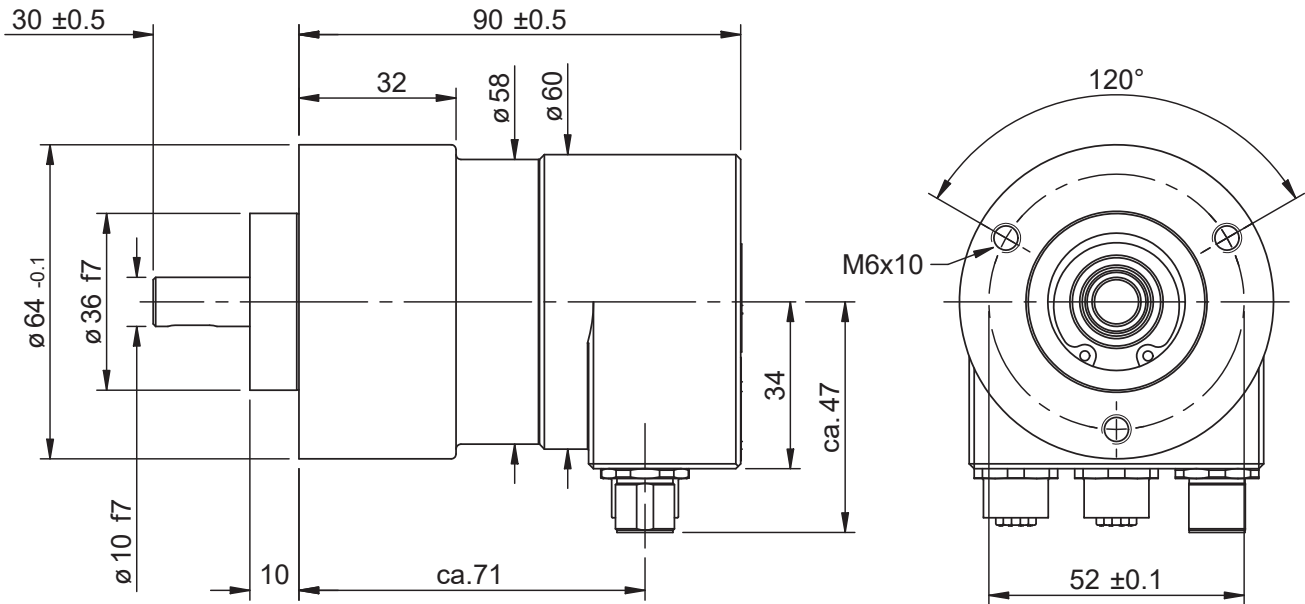
**Absolute encoder model TRT**

**Installation drawings**

**Design form 64 with heavy duty flange, order number: TRT64-HPA8192R4096C4MT01**

Shaft  $\varnothing$  10 mm with flat

Dimensions in mm



- Suitable mounting bracket MW-S-03, see [MZ10111](#)